
Modeling of Fairness

– Distribution of Efficiency Gains in Supply Webs
from a Game-theoretic Point of View –

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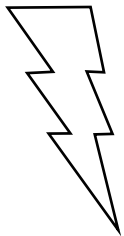
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- 1 Problem identification
- 2 Requirements to restrict the solution space
- 3 Calculation rule for τ -value
- 4 Concluding remarks

Supply chain management:

- Realizing efficiency gains by coordinating the activities of all supply chain / supply web participants
- ...



Problems

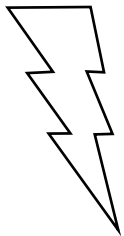
- distribution of the efficiency gains among partially autonomous actors in a supply web
- each actor is interested in maximizing his own gain
- built-in conflict between cooperation and defection

Generic distribution problem:

- Find a distribution of efficiency gains ensuring that
 - the actors in a supply web are willing to cooperate with each other and that
 - the actors accept as “fair”

Standard approach in game theory:

- Specifying a set of “reasonable” axioms / applicability conditions of a solution concept
- Is the solution concept the only one that is capable of fulfilling a set of axioms?



Problems

- justification of the axioms
- difficult to detect the connection between axioms and the respective real problems

alternative approach:

- Starting from the real problem to distribute efficiency gains among the actors in a supply web
- The solution concept should be derivable from plausible requirements oriented towards the real problem



Definition of five requirements

Requirements to restrict the solution space

First requirement:

Individual rationality

- Perfect rationality: each actor maximizes her or his individual utility
 - no envy effects
 - information processing capacity of the actors is not restricted
 - ...
- It would **not** be **rational** for an actor A_n to **participate in the supply web** within the coalition K_0 , if this coalition yields a smaller utility in comparison to realizing the amount $c(\{A_n\})$ **outside the supply web**.
- The condition of individual rationality can be formulated with the function c as follows:

$$\forall L_v \in \mathbb{R}_{\geq 0}^N : L_v = \begin{pmatrix} v_1 \\ \dots \\ v_N \end{pmatrix} \geq \begin{pmatrix} c(\{A_1\}) \\ \dots \\ c(\{A_N\}) \end{pmatrix}$$

→ solution space is restricted to the first quadrant

Requirements to restrict the solution space

Second requirement

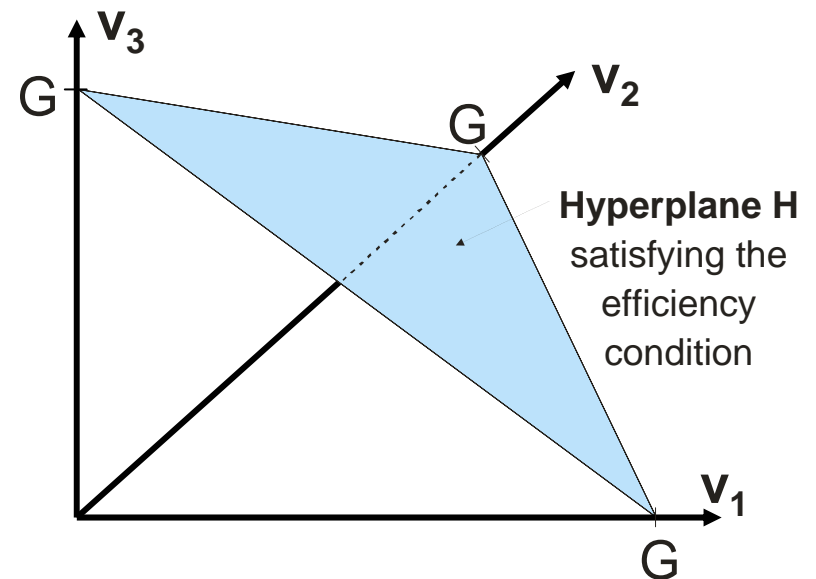
Efficiency condition

- The efficiency gain G is distributed completely among the coalition $K_0 = \{A_1, \dots, A_N\}$ of all actors
 - It would be **irrational** to distribute less than the efficiency gain G
 - loss of Pareto Optimality
 - It would be **irrational** to distribute more than the efficiency gain G

$$\forall L_v \in \mathbb{R}_{\geq 0}^N : L_v = \begin{pmatrix} v_1 \\ \dots \\ v_N \end{pmatrix} \rightarrow \sum_{n=1}^N v_n = G$$

→ Hyperplane H as the set of all solutions that are satisfying the condition:

$$\sum_{n=1}^N v_n = G$$



Requirements to restrict the solution space

Third requirement

Rationality condition for maximum allocable shares of the gain

- The N-1 actors of the so called marginal coalition MK_n with $MK_n = K_0 \setminus \{A_n\}$ grant actor A_n at most the share $v_{n,max}$ of the efficiency gain G , if actor A_n would leave the great coalition $K_0 = \{A_1, \dots, A_N\}$, so that the efficiency gain G would decrease.

→ Rationality condition:

$$\forall n = 1, \dots, N \quad \forall v_n \in \mathbb{R} : v_n \leq v_{n,max} \wedge v_{n,max} = c(K_0) - c(MK_n) = G - c(MK_n)$$

In the solution space the point, in which the maximum allocable share $v_{n,max}$ of the gain is assigned to each actor A_n , is called *upper bound UB* or *ideal point*.

Requirements to restrict the solution space

Fourth requirement

Rationality condition for minimal allocable shares of the gain

- Each actor A_n receives at least the share $v_{n,\min}$ of the efficiency gain G , so that she or he could believably threaten to found an outsider coalition $AK_{n,q}$
- **Side payments:** Actor A_n makes an offer (= side payment) to the other actors in an outsider coalition $AK_{n,q}$.
The side payment ensures that the utility of each other actor is the same as his or her maximum utility in the great coalition K_0 .
→ The actors in an outsider coalition have no incentives to remain in the great coalition K_0 .

Complete rationality condition for minimal allocable shares of the gain:

$$\forall n = 1, \dots, N \quad \forall v_n \in \mathbb{R}_{\geq 0} : \quad v_n \geq v_{n.\min} \quad \wedge \quad v_{n.\min} = \max \{c_{n.1}, c_{n.2}, 0\}$$

with

$$c_{n.1} = \max \left\{ \begin{array}{l} c(\{A_n\} | AK_{n.q}) = c(AK_{n.q}) - \sum_{m \in (N_{n.q} \setminus \{n\})} v_{m.\max} \quad | \quad \dots \\ \emptyset \subset AK_{n.q} \subset A \quad \wedge \quad \{A_n\} \subset AK_{n.q} \end{array} \right\}$$

$$c_{n.2} = c(\{A_n\} | AK_{n.q}) = c(\{A_n\}) \quad \text{for} \quad AK_{n.q} = \{A_n\}$$

→ lower bound LB / **threat point**

Requirements to restrict the solution space

Fifth requirement

Operational fairness criterion

- The greater bargaining power of an actor A_n is, the greater is her or his share v_n of the efficiency gain G .
 - The bargaining power of an actor A_n is affected by two opposed effects:
 - On the one hand the bargaining power of an actor A_n is measured by the **contribution** $v_{n,max}$ the actor would make, if she or he would take part in the marginal coalition MK_n and thus would make this marginal coalition a great coalition K_0 .
 - **positive** network effect
 - On the other hand the bargaining power of an actor A_n is measured by her or his **threat potential** $v_{n,min}$ build up of the believable threat to found an outsider coalition $AK_{n,q}$.
 - **negative** network effect

Calculation rule for τ -value

$\forall n = 1, \dots, N:$ normalized bargaining powers

$$V_{n,\tau} = \begin{cases} \alpha \cdot \frac{V_{n,\max}}{\sum_{n=1}^N V_{n,\max}} \cdot G + \beta \cdot \frac{V_{n,\min}}{\sum_{n=1}^N V_{n,\min}} \cdot G & ; \text{ if } \sum_{n=1}^N V_{n,\max} \neq \sum_{n=1}^N V_{n,\min} \\ V_{n,\max} = V_{n,\min} & ; \text{ if } \sum_{n=1}^N V_{n,\max} = \sum_{n=1}^N V_{n,\min} \end{cases}$$

with

Weighting of the bargaining powers

$$\alpha = \frac{G - \sum_{n=1}^N V_{n,\min}}{\sum_{n=1}^N V_{n,\max} - \sum_{n=1}^N V_{n,\min}} \cdot \frac{\sum_{n=1}^N V_{n,\max}}{G} \quad \beta = \frac{\sum_{n=1}^N V_{n,\max} - G}{\sum_{n=1}^N V_{n,\max} - \sum_{n=1}^N V_{n,\min}} \cdot \frac{\sum_{n=1}^N V_{n,\min}}{G}$$

Calculation rule for τ -value

Equivalent representation of the τ -value as

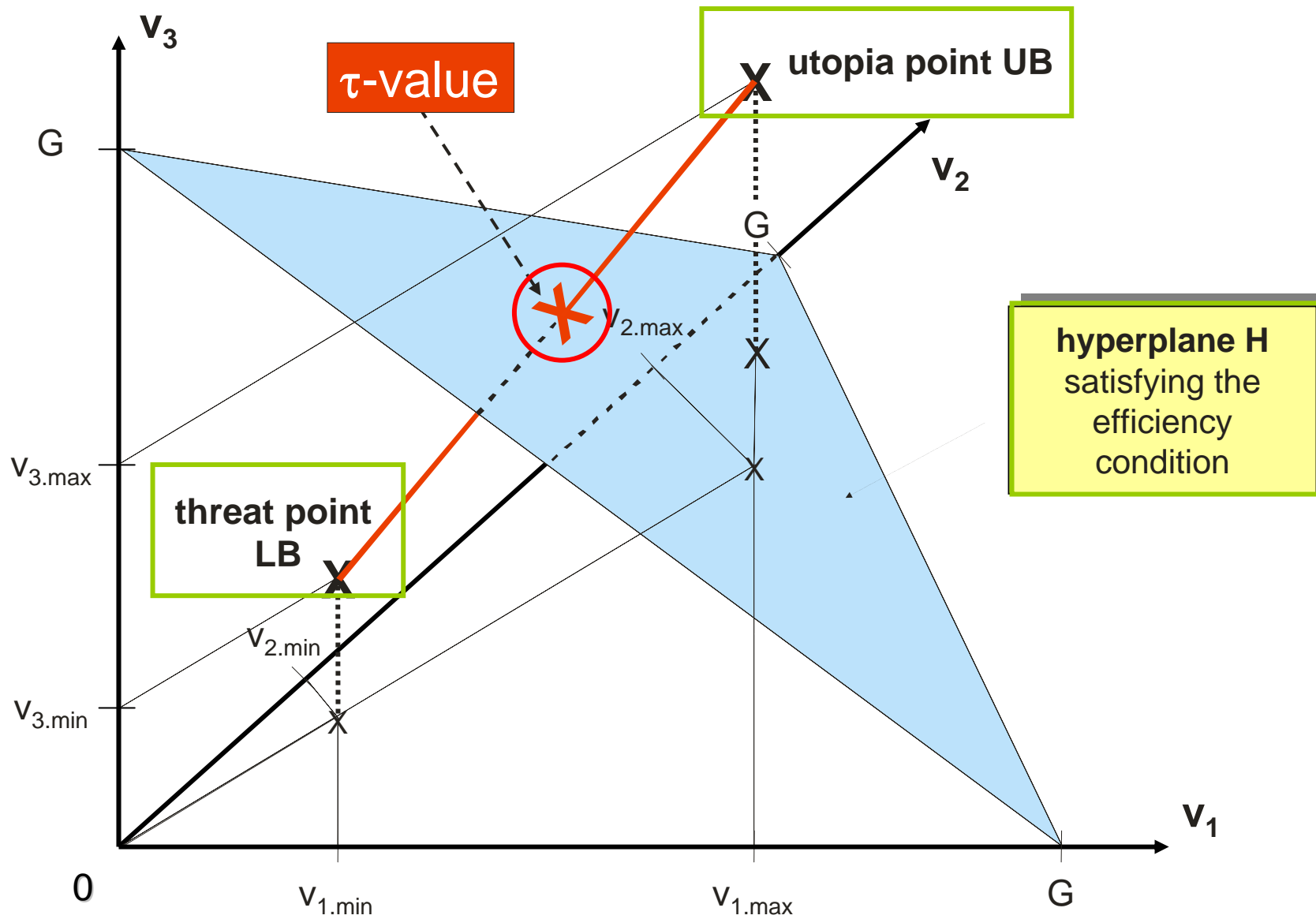
- linear combination of **utopia point UB** and **threat point LB**
- lying on the hyperplane H within the solution space and thus satisfying the efficiency condition

$$\forall n = 1, \dots, N: v_{n,\tau} = \gamma \cdot v_{n,\max} + (1 - \gamma) \cdot v_{n,\min}$$

with

$$\gamma = \begin{cases} \frac{G - \sum_{n=1}^N v_{n,\min}}{\sum_{n=1}^N v_{n,\max} - \sum_{n=1}^N v_{n,\min}} & ; \text{ if } \sum_{n=1}^N v_{n,\max} \neq \sum_{n=1}^N v_{n,\min} \\ 0 \vee 1 & ; \text{ if } \sum_{n=1}^N v_{n,\max} = \sum_{n=1}^N v_{n,\min} \end{cases}$$

Concluding remarks



- + τ -value solution concept fulfills the five requirements
- + good reasons to accept a distribution of the efficiency gain G among the N actors as **fair**
 - share of the efficiency gain depends on the actor's bargaining power
 - compromise solution
 - distribution result is explicit
- + τ -value solution concept can be communicated easily in comparison to other game theoretic concepts (Shapley-Value, Nucleolus)
- Assumption that the bargaining power can be measured by the positive and negative network effects
- requires data on coalitions

Thank you for your time and attention!

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